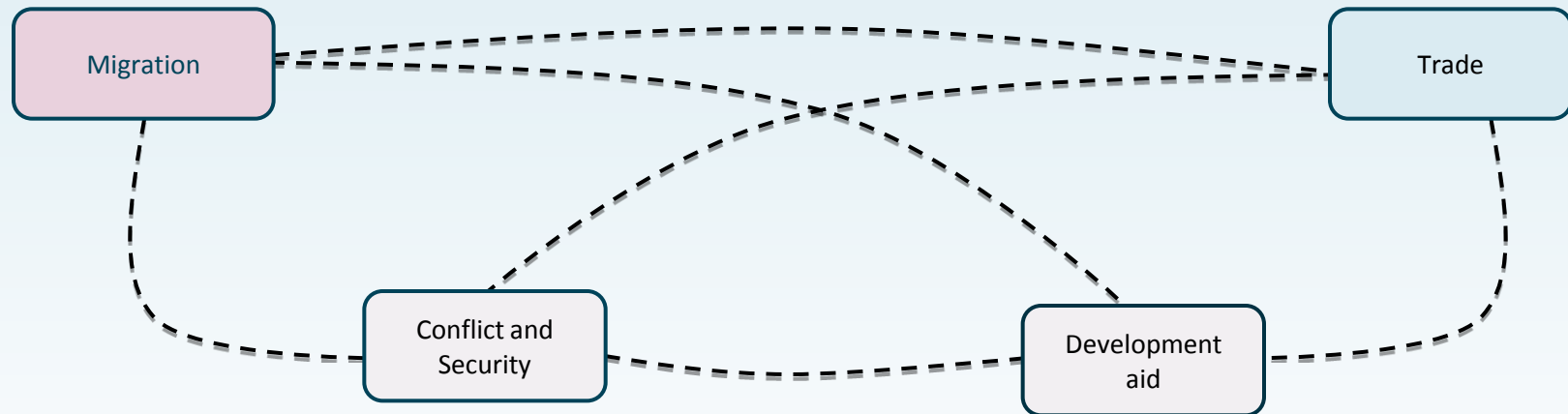


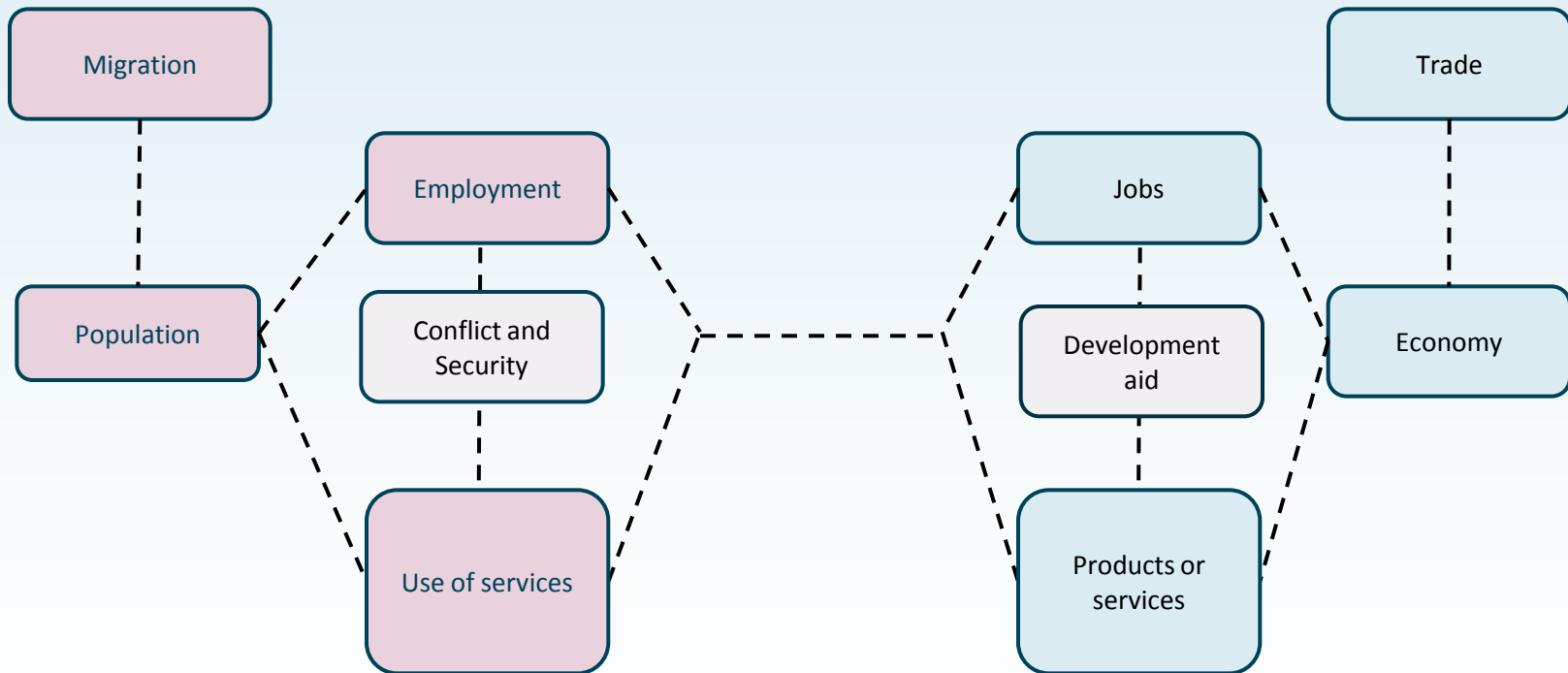
Using complex systems methods to model global dynamics



The global dynamics project



The global dynamics project



Discrete choice

Migration

People choose to migrate based on population, proximity, economy, job markets

Trade

Consumers buy goods because of price and ease of access

Conflict and Security

Nations place arms or troops in line with threat and strategic value

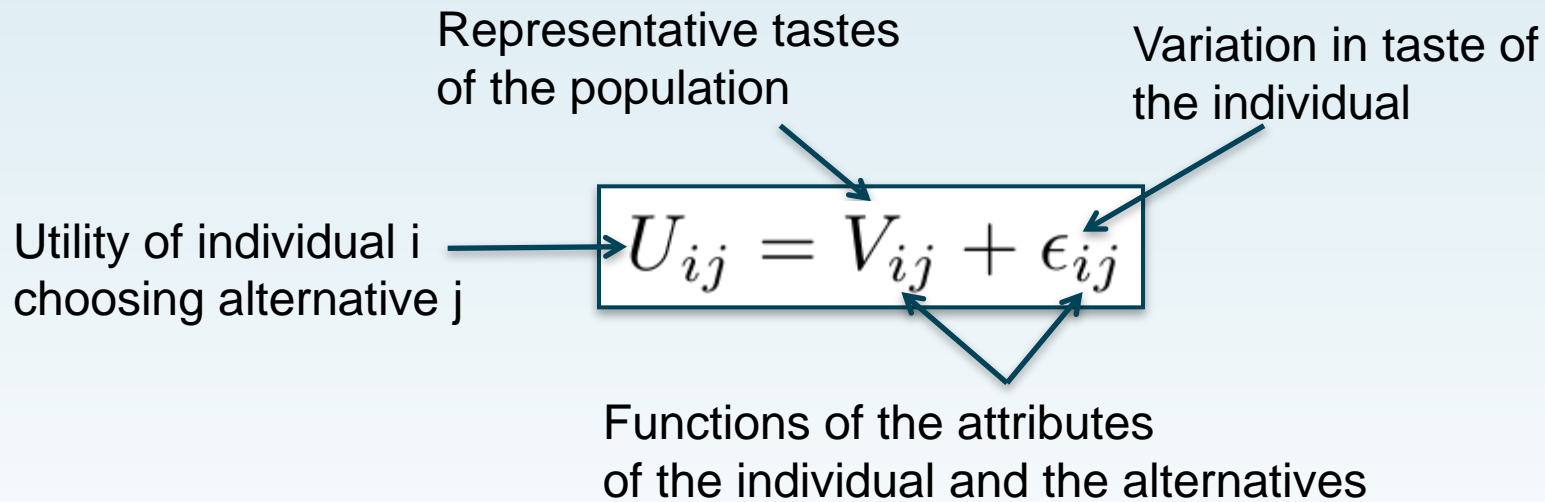
Development aid

Aid is offered based on diplomatic relationship, economic relationship and level of urgency

Discrete Choice

- The set of alternatives must be exhaustive
- The alternatives must be mutually exclusive
- The set must contain a finite number of alternatives

The McFadden conditional logit model



$$P(\text{individual } i \text{ chooses } j) = \frac{\exp(V_{ij})}{\sum_k \exp(V_{ik})}$$

Migration as a discrete choice problem

$$V_{ij} = \alpha \ln(P_j) - \beta d_{ij}$$

Distance between origin and destination

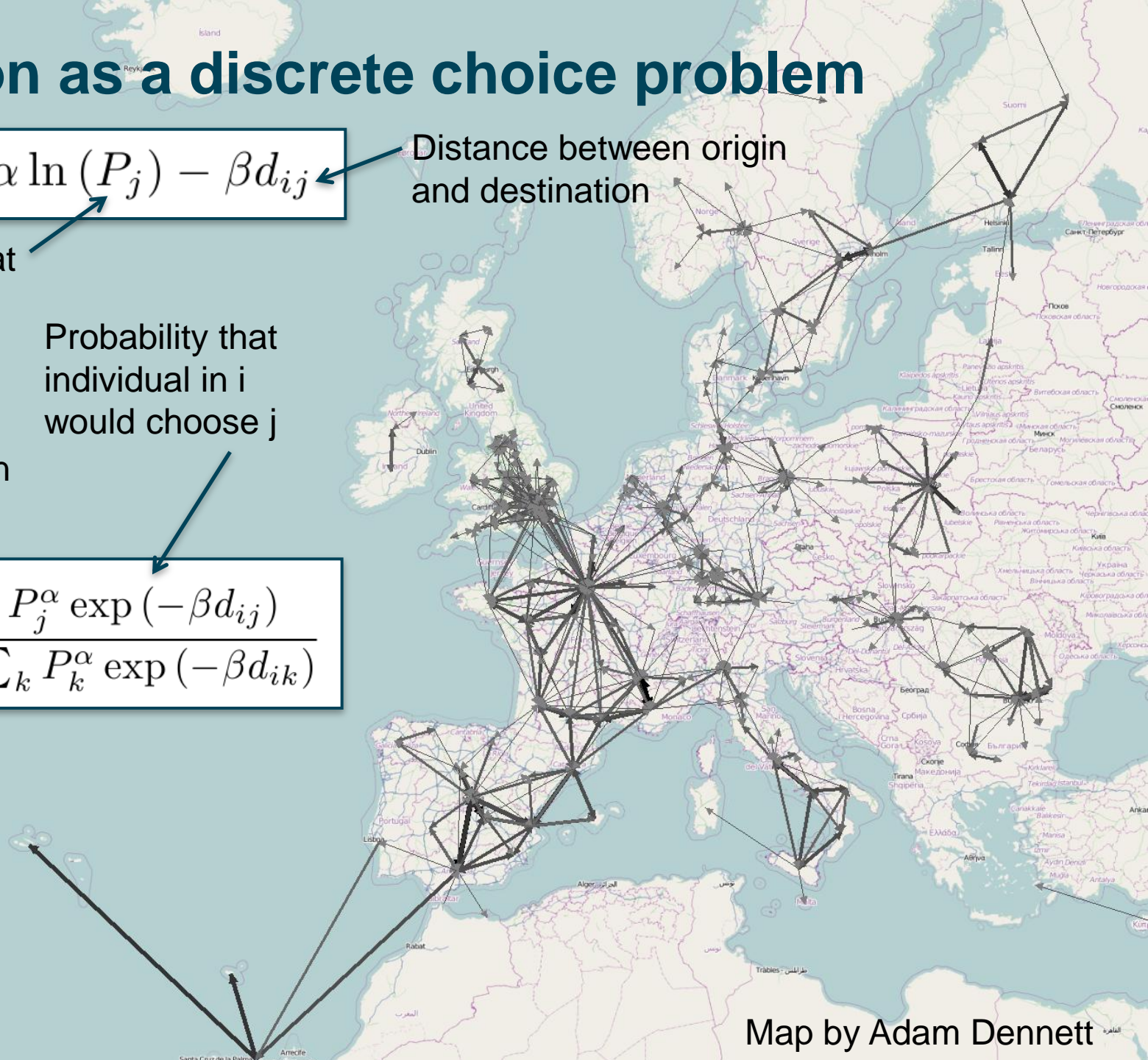
Population at destination

Probability that individual in i would choose j

Migration flows between i and j

$$Y_{ij} = P_i \frac{P_j^\alpha \exp(-\beta d_{ij})}{\sum_k P_k^\alpha \exp(-\beta d_{ik})}$$

Population at origin



Other migration models

Conditional logit model:

Entropy maximising spatial interaction

All these models can be considered algebraically equivalent.

tion
on

Overall level of migration

Push term for each region

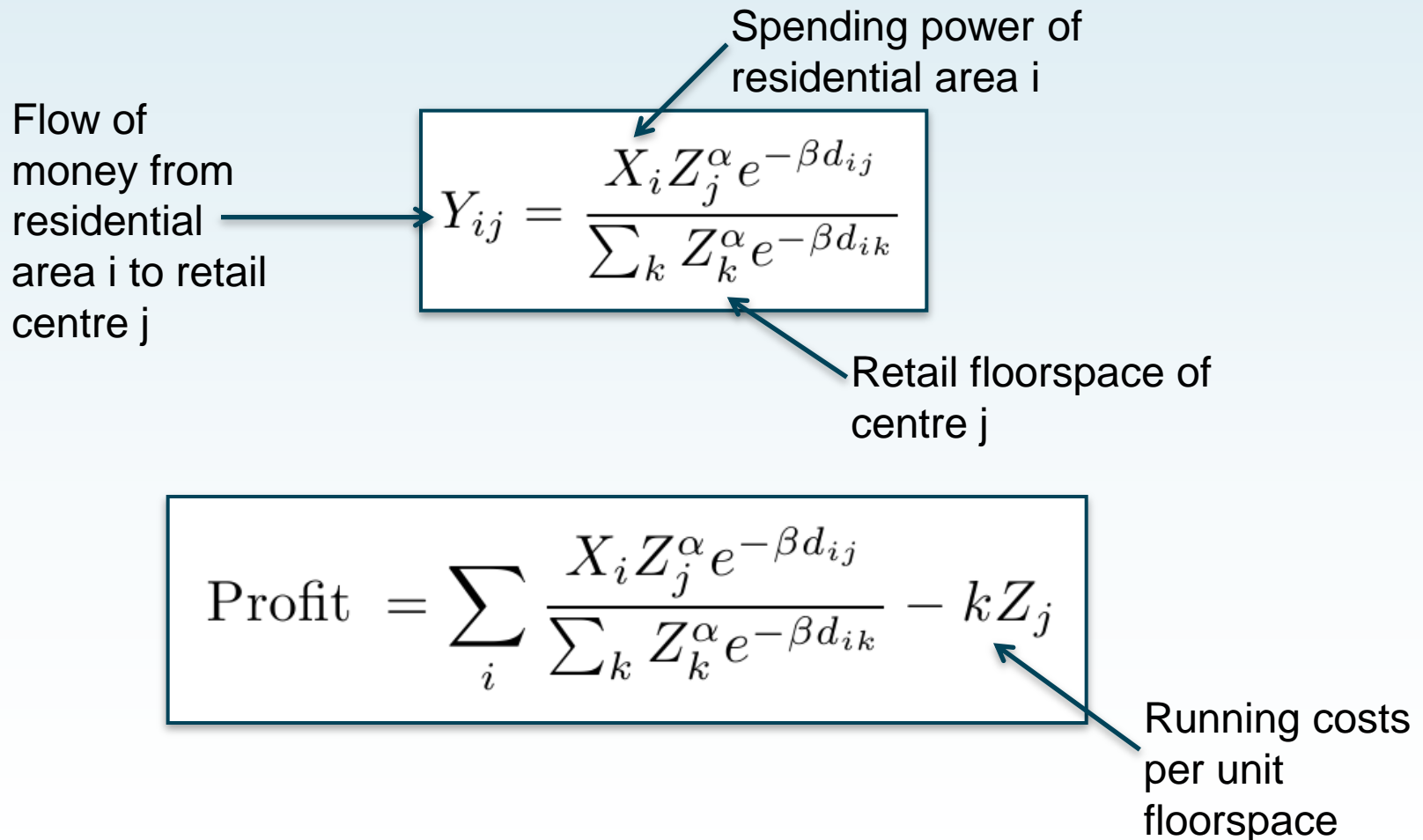
Pull term for each region

Interaction between zones

$$Y_{ij} = \frac{kP_i P_j}{f(d_{ij})}$$

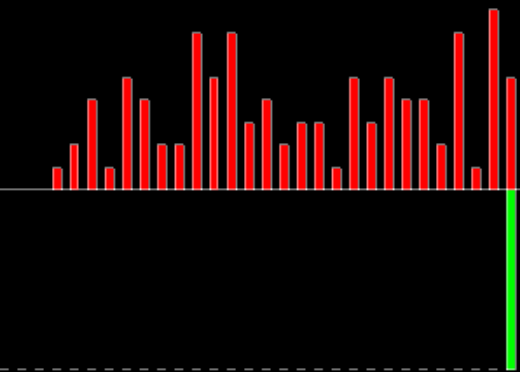
Embedding discrete choice models into dynamics

Example 1: the retail model



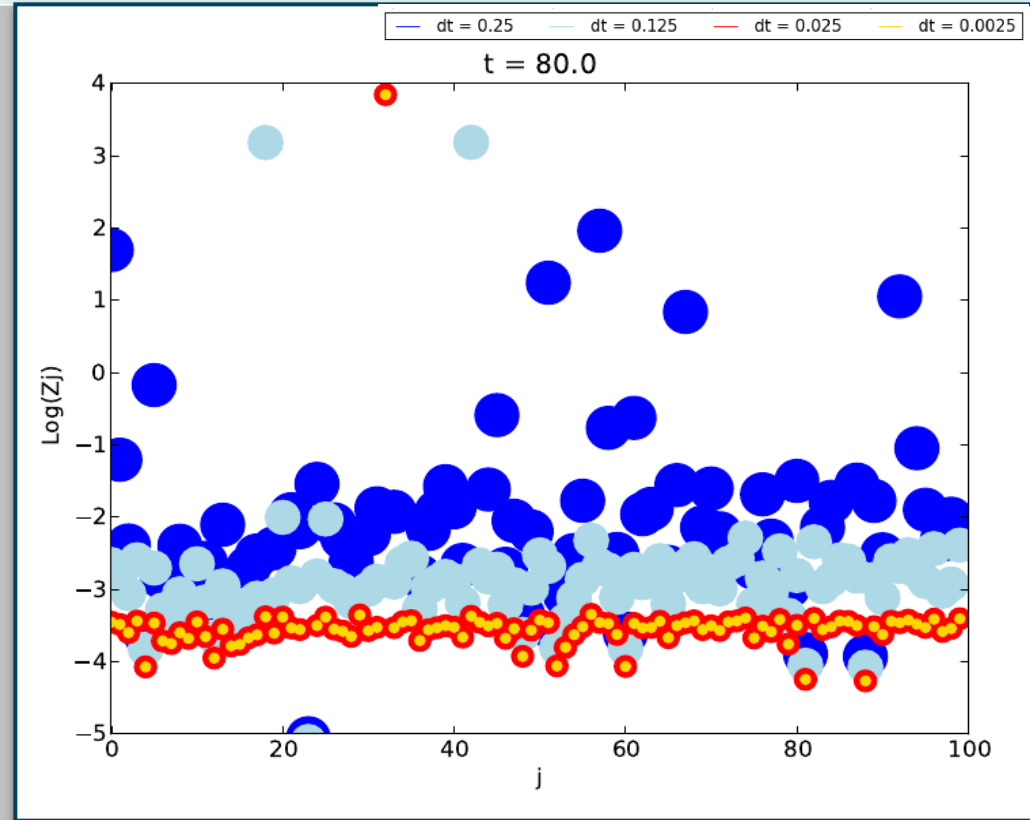
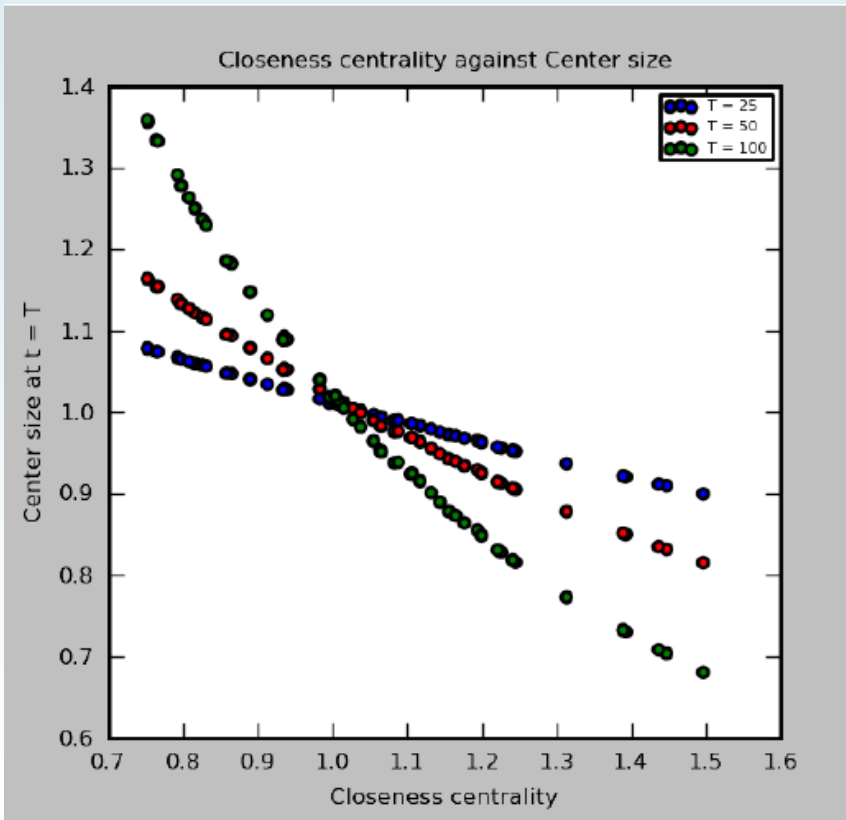
Visualisation by Martin Zaltz-Austwick

$$\frac{1}{Z_j} \frac{\partial Z_j}{\partial t} = \sum_i \frac{X_i Z_j^\alpha e^{-\beta d_{ij}}}{\sum_k Z_k^\alpha e^{-\beta d_{ik}}} - k Z_j$$



Embedding discrete choice models into dynamics

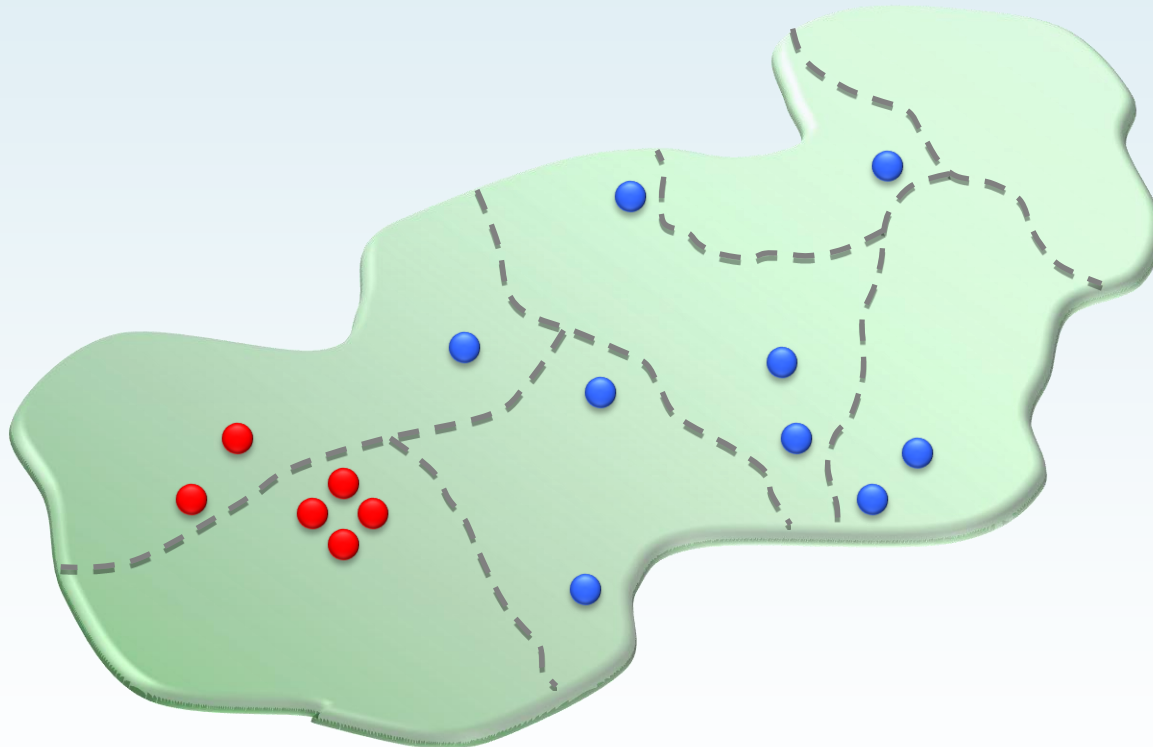
Example 1: the retail model



$$\frac{1}{Z} \frac{\partial Z}{\partial t} = \iint \frac{Z^\alpha(x, y, t) X(\bar{x}, \bar{y}) \exp(-\beta|r(x, y) - \bar{r}(\bar{x}, \bar{y})|)}{\iint Z^\alpha(u, v, t) \exp(-\beta|r(u, v) - \bar{r}(\bar{x}, \bar{y})|)} d\bar{x} d\bar{y} - kZ(x, y, t)$$

Embedding discrete choice models into dynamics

Example 2: A Blotto game of threat

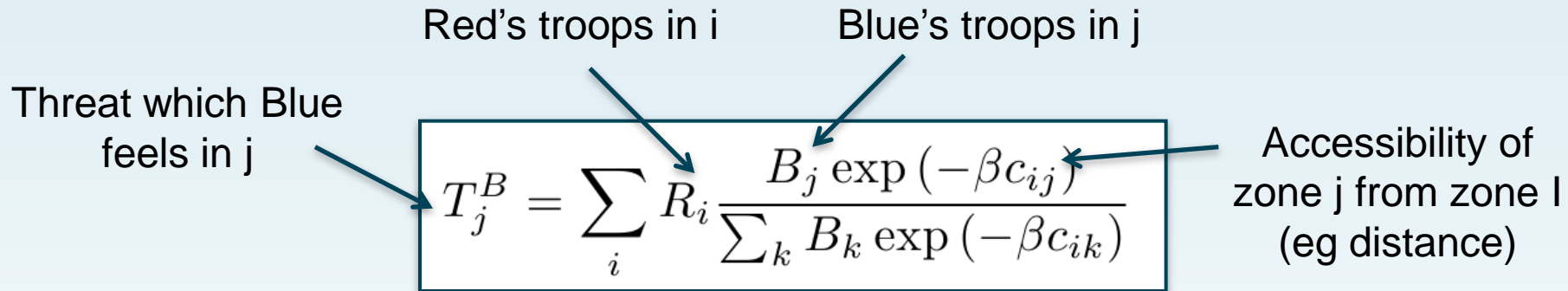


Embedding discrete choice models into dynamics

Example 2: A blotto game of threat

Red's troops in i Blue's troops in j

Threat which Blue feels in j Accessibility of zone j from zone i (eg distance)

$$T_j^B = \sum_i R_i \frac{B_j \exp(-\beta c_{ij})}{\sum_k B_k \exp(-\beta c_{ik})}$$


Normalise based on Blue's size in j :

$$\tau_j^B = \sum_i \frac{R_i \exp(-\beta c_{ij})}{\sum_k B_k \exp(-\beta c_{ik})}$$

Embedding discrete choice models into dynamics

Example 2: A Blotto game of threat

$$\Pi^B = \sum_j \text{sgn}(\tau_j^R - \tau_j^B) |B_j - R_j|^P$$

Zone 1	Zone 2
Blue: 1	Blue: 1
Red: 2	Red: 0

$$c_{ij} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

